13.2: Differentiation and Integration

Differentiation of vector functions: Differentiate each component Example: <u>r</u>(t) = \lap{t}, t^2, t^3 \lap{a} <u>r</u>'(t) = \lap{dt}{dt}, \frac{dt^2}{dt}, \frac{dt^3}{dt} \rangle = \lap{1}, 2t, 3t^2 \rangle

Second derivative <u>r</u>''(t) = \lap(r')' Example: <u>r</u>(t) = \lap{t}, t^2, t^3 \lap{a} <u>r</u>''(t) = \lap{0}, 2, 6t \rangle

■ Integration of vector functions: Integrate each component

$$\begin{array}{ll} \textbf{Example:} \ \underline{r}(t) = \langle t, \ t^2, \ t^3 \rangle \\ \\ \int \underline{r}(t) \ \mathrm{d}t = \left\langle \int t \ \mathrm{d}t, \ \int t^2 \ \mathrm{d}t, \int t^3 \ \mathrm{d}t \right\rangle = \left\langle \frac{t^2}{2} + C_1, \ \frac{t^3}{3} + C_2, \ \frac{t^4}{4} + C_3 \right\rangle \end{array}$$

13.2: Differentiation Rules for Vector Functions

For sufficiently smooth vector functions $\underline{u}(t)$ and $\underline{v}(t)$ and scalar functions f(t)

1. Sum rule:
$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\underline{u} + \underline{v}\right] = \frac{\mathrm{d}\underline{u}}{\mathrm{d}t} + \frac{\mathrm{d}\underline{v}}{\mathrm{d}t}$$

2. Product rule:
$$\frac{\mathrm{d}}{\mathrm{d}t} [f \ \underline{u}] = \frac{\mathrm{d}f}{\mathrm{d}t} \ \underline{u} + f \ \frac{\mathrm{d}\underline{u}}{\mathrm{d}t}$$

3. Dot product rule:
$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\underline{u} \cdot \underline{v}\right] = \frac{\mathrm{d}\underline{u}}{\mathrm{d}t} \cdot \underline{v} + \underline{u} \cdot \frac{\mathrm{d}\underline{v}}{\mathrm{d}t}$$

4. Cross product rule:
$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\underline{u} \times \underline{v}\right] = \frac{\mathrm{d}\underline{u}}{\mathrm{d}t} \times \underline{v}$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\underline{u} \times \underline{v} \right] = \frac{\mathrm{d}\underline{u}}{\mathrm{d}t} \times \underline{v} + \underline{u} \times \frac{\mathrm{d}\underline{v}}{\mathrm{d}t}$$

5. Chain rule:

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\underline{u}(f(t)) \right] \; = \; \frac{\mathrm{d}\underline{u}}{\mathrm{d}t}(f(t)) \; \frac{\mathrm{d}f}{\mathrm{d}t}(t)$$

13.2: Tangent Vector and Tangent Line

Let C be the curve defined by $\underline{r}(t)$

Tangent vector: $\underline{r}'(t)$ is tangent to curve C

- $\underline{r}'(t)$ is in direction of the curve (<u>not</u> the opposite direction)
- $\underline{r}'(t)$ needs to exist and $\underline{r}'(t) \neq \underline{0}$ ($\underline{0}$ has no direction)

• Unit tangent vector:
$$\underline{T}(t) = \frac{\underline{r}'(t)}{|\underline{r}'(t)|}$$
 if $\underline{r}'(t) \neq \underline{0}$

Tangent line to curve C at point (x_0, y_0, z_0)

- Vector eqn: $\underline{l}(t) = \underline{r}_0 + t\underline{v}$ with $\underline{r}_0 = \underline{r}(t_0)$ and $\underline{v} = \underline{r}'(t_0)$ Or: $\langle x(t), y(t), z(t) \rangle = \langle x_0, y_0, z_0 \rangle + t \langle x'(t_0), y'(t_0), z'(t_0) \rangle$
- Meaning: Equation of a line with tangent vector as direction vector
- t_0 is the *t*-value corresponding to (x_0, y_0, z_0)

13.2: Intersections and Collisions

■ Intersection of curve and surface: Position on curve and surface is equal

- Typically a set of points
- See 12.5 for intersections of lines and planes

Intersection of 2 curves: positions are equal $\underline{r}_1(t) = \underline{r}_2(s)$

- Rare in real life, in 2204 typically a point
- Note time t and s do <u>not</u> need to be equal
- **Collisions:** position and time are equal $\underline{r}_1(t) = \underline{r}_2(t)$
 - Very rare in real life, in 2204 typically a point or no collision
 - Note both position <u>and</u> time are equal