

Global Convection in Earth's Mantle: Advanced Numerical Methods for Forward and Inverse Modeling

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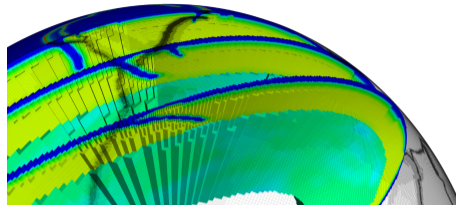
Motivation: Understanding of Earth's fundamental properties

Simulating realistic high-resolution models:

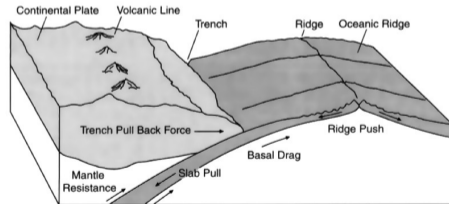
- ▶ Global mantle convection & associated plate tectonics
- ▶ Resolutions to faulted plate boundaries
- ▶ Nonlinear viscous fluid flow

Learning properties of Earth's rheology:

- ▶ What we know: Observational **data** of plate motions at the surface, topography, surface strain rates, estimates of average viscosities, etc.
- ▶ What we want: **Parameters** in constitutive laws and plate coupling strength that are **consistent with data and model**; Uncertainties w.r.t. available data



Computational mesh that resolves viscosity (colors).

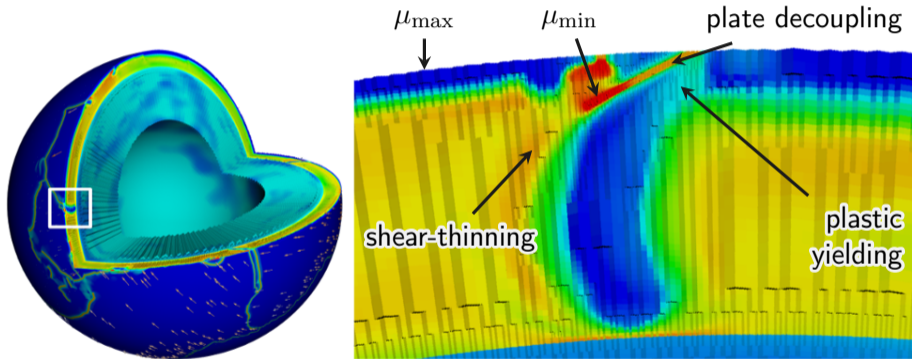


Underlying forces (Credit: Schubert, Turcotte, Olsen).

Simulation

Approach for simulation

Model PDE: present day instantaneous flow modeled by **incompressible, nonlinear Stokes Rheology / effective viscosity: shear-thinning with plastic yielding**, and upper/lower bounds



Colors represent viscosity ($\mu_{\max}/\mu_{\min} = 10^6$).

Approach for simulation

Model PDE: present day instantaneous flow modeled by **incompressible, nonlinear Stokes**

$$\begin{aligned} -\nabla \cdot [\mu(\mathbf{x}, \dot{\epsilon}_{\text{II}}(\mathbf{u})) (\nabla \mathbf{u} + \nabla \mathbf{u}^T)] + \nabla p &= \mathbf{f} && \text{viscosity } \mu, \text{ RHS forcing } \mathbf{f} \\ -\nabla \cdot \mathbf{u} &= 0 && \text{velocity } \mathbf{u}, \text{ pressure } p \end{aligned}$$

- ▶ Free-slip boundary conditions (tangential velocities at the surface are output of the model)
- ▶ Temperature structure from seismic models and convergence rate of slabs
- ▶ Fault weak zones based on *Slab1.0* compilation of models for subduction zones

Rheology / effective viscosity: **shear-thinning with plastic yielding**, and upper/lower bounds

$$\mu(\mathbf{x}, \dot{\epsilon}_{\text{II}}(\mathbf{u})) := \mu_{\min} + \min \left(\frac{\tau_{\text{yield}}}{2\dot{\epsilon}_{\text{II}}(\mathbf{u})}, w(\mathbf{x}) \min \left(\mu_{\max}, a(T(\mathbf{x}))^{\frac{1}{n}} \dot{\epsilon}_{\text{II}}(\mathbf{u})^{\frac{1}{n}-1} \right) \right)$$

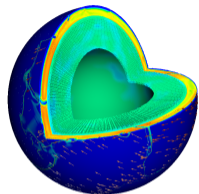
- ▶ Plates are modeled by high-viscosity: $a(T(\mathbf{x}))$ depends exponentially on T
- ▶ Plate boundaries are narrow zones of weak viscosity: $10^{-6} \leq w(\mathbf{x}) \leq 1$

Severe challenges for parallel scalable implicit solvers

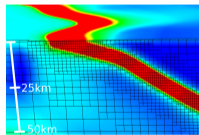
... arising from global models of Earth's mantle convection:

- ▶ Severe nonlinearity, heterogeneity, and anisotropy (upon linearization)
- ▶ **Sharp viscosity gradients** in narrow regions (change by $\mathcal{O}(10^6)$ in ~ 5 km)
- ▶ **Wide range of spatial scales** and highly localized features, e.g., plate boundaries of size $\mathcal{O}(1$ km) influence plate motion at continental scales of $\mathcal{O}(1000$ km)
- ▶ Adaptive refinement of computational mesh is essential
- ▶ High-order finite elements $\mathbb{Q}_k \times \mathbb{P}_{k-1}^{\text{disc}}$, order $k \geq 2$, with **local mass conservation**; yields a difficult to deal with discontinuous, modal pressure approximation

A resolved model has about 1 billion DOFs (with aggressive adaptivity), because smallest mesh elements ~ 1 km; Runs on 10K–100K computing cores.



Colors represent viscosity, arrows show plate velocities.



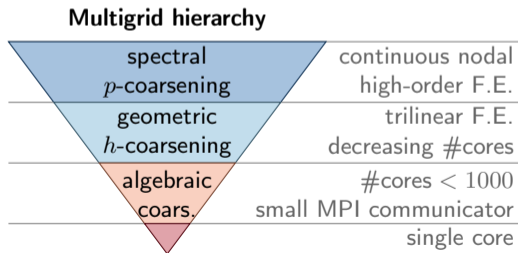
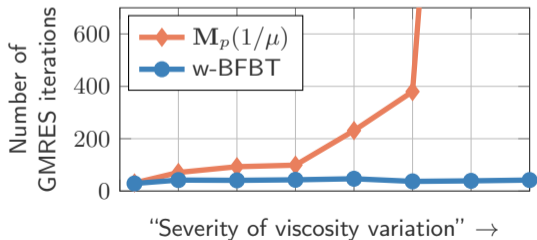
Fault zone (red) between stationary and subducting plate.

Solver highlights: Viscosity variation-robust preconditioning and scalable parallel multigrid for adaptive high-order F.E.

Stokes preconditioning: $\begin{bmatrix} \mathbf{A} & \mathbf{B}^T \\ \mathbf{B} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \tilde{\mathbf{A}} & \mathbf{B}^T \\ \mathbf{0} & \tilde{\mathbf{S}} \end{bmatrix}^{-1} \begin{bmatrix} \tilde{\mathbf{u}} \\ \tilde{\mathbf{p}} \end{bmatrix} = \begin{bmatrix} -\mathbf{r}_1 \\ -\mathbf{r}_2 \end{bmatrix} \quad \tilde{\mathbf{A}}^{-1} \approx \mathbf{A}^{-1} \rightarrow \text{MG V-cycle}$
 $\tilde{\mathbf{S}}^{-1} \approx (\mathbf{B}\mathbf{A}^{-1}\mathbf{B}^T)^{-1}$

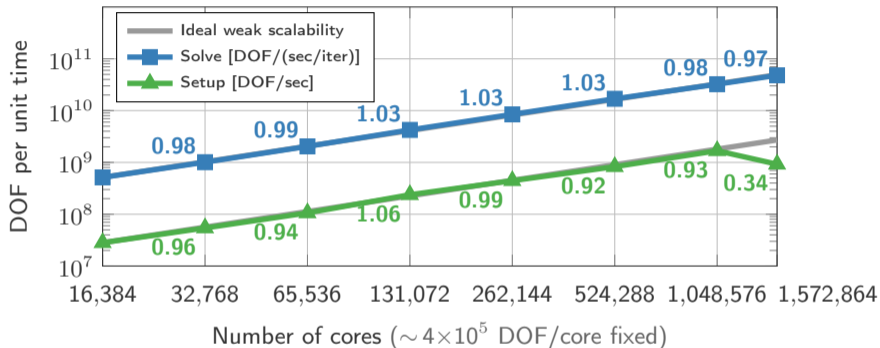
Schur complement preconditioning: $\tilde{\mathbf{S}}^{-1} := \underbrace{(\mathbf{B}\mathbf{C}_w^{-1}\mathbf{B}^T)^{-1}}_{\rightarrow \text{MG V-cycle}} (\mathbf{B}\mathbf{C}_w^{-1}\mathbf{A}\mathbf{D}_w^{-1}\mathbf{B}^T) \underbrace{(\mathbf{B}\mathbf{D}_w^{-1}\mathbf{B}^T)^{-1}}_{\rightarrow \text{MG V-cycle}}$

Choice of diagonal weighting matrices $\mathbf{C}_w = \mathbf{D}_w$ is critical for efficacy & robustness.



Solver highlights: Parallel weak scalability on Sequoia (BlueGene/Q)

Parallel scalability of linear iterative solvers to 1.6M cores (collaboration with IBM Research, Zurich):



- ▶ Excellent parallel scalability while maintaining optimal algorithmic performance w.r.t. mesh refinement; nearly optimal w.r.t. higher discretization order
- ▶ Full nonlinear Stokes solver: Inexact Newton–Krylov with nonlinear preconditioning and grid continuation for highly nonlinear models of Earth’s mantle

Inference

Approach for inference: From data to parameters consistent with model

General procedure for inference from data consistent with a model (physical, statistical, etc.):

1. **Question:** Start with a scientific question, e.g., quantify forces in deep Earth.
2. **Data collection:** Gather data relevant to the question, e.g., plate motions at the surface.
3. **Model selection:** Construct a model that is *appropriate* to the problem and data, moreover, select parameters for inference, e.g., global mantle convection model with plate coupling strength as parameters.
4. **Parameter estimation:** Find the parameters in the model, which often requires minimizing the difference between model output and data (in some suitable metric).
5. **Validation:** Inspect if the model and parameters are consistent with knowledge or data that was excluded from estimation, e.g., average viscosity or topography.
6. **Prediction:** Estimate the quantities of interest and their uncertainties that are associated with the initial scientific question.

Approach for inference: Global mantle convection & plate tectonics

Data: Challenging because of limited amount

- ▶ Current plate motion of rigid plates from GPS and magnetic anomalies recorded in bands perpendicular to seafloor spreading

Model: Challenging because of computational complexity

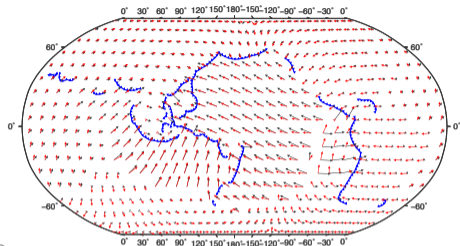
- ▶ Incompressible, nonlinear Stokes PDE:

$$-\nabla \cdot [\mu(\mathbf{x}, \dot{\epsilon}_{II}(\mathbf{u})) (\nabla \mathbf{u} + \nabla \mathbf{u}^T)] + \nabla p = \mathbf{f}, \quad -\nabla \cdot \mathbf{u} = 0$$

- ▶ Effective viscosity: $\mu(\mathbf{x}, \dot{\epsilon}_{II}(\mathbf{u})) := \mu_{\min} + \min \left(\frac{\tau_{\text{yield}}}{2\dot{\epsilon}_{II}(\mathbf{u})}, w(\mathbf{x}) \min \left(\mu_{\max}, a(T(\mathbf{x}))^{\frac{1}{n}} \dot{\epsilon}_{II}(\mathbf{u})^{\frac{1}{n}-1} \right) \right)$

Parameters: Challenging because of vastly different scales of sensitivity

- ▶ Global parameters: scaling factors, activation energy in Arrhenius law $a(T(\mathbf{x}))$, stress exponent n , yield strength τ_{yield}
- ▶ Local coupling strength $w(\mathbf{x})$, i.e., energy dissipation between adjacent plates



Data (black) vs. model (red) (Credit: J. Hu).

Systematic inversion of uncertain parameters consistent with data & model

Given:

- ▶ Model PDE (forward problem), here incompressible, nonlinear Stokes: $\mathcal{A}(m, u) = f$
- ▶ Map of model output (dependent on parameters m) to observations: $\mathcal{F}(u(m))$
- ▶ Assume data d contains normally distributed additive noise, $\mathcal{N}(0, \mathcal{C}_{\text{noise}})$
- ▶ Assume prior of the parameters m is normally distributed, $\mathcal{N}(m_{\text{pr}}, \mathcal{C}_{\text{pr}})$

Want: Description of the **posterior density of the parameters** (using Bayes' theorem)

$$\pi_{\text{post}}(m) \propto \exp\left(-\frac{1}{2} \|d - \mathcal{F}(u(m))\|_{\mathcal{C}_{\text{noise}}^{-1}}^2 - \frac{1}{2} \|m - m_{\text{pr}}\|_{\mathcal{C}_{\text{pr}}^{-1}}^2\right)$$

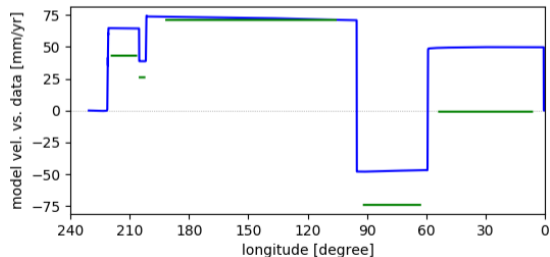
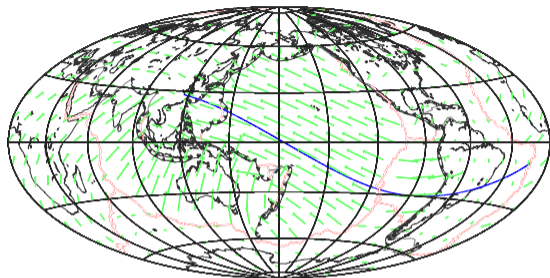
Computationally feasible: Using adjoints for gradient computation & BFGS approximation of Hessian

- ▶ Find the maximum of $\pi_{\text{post}}(m)$ by solving an **optimization problem constraint by the model PDE:**

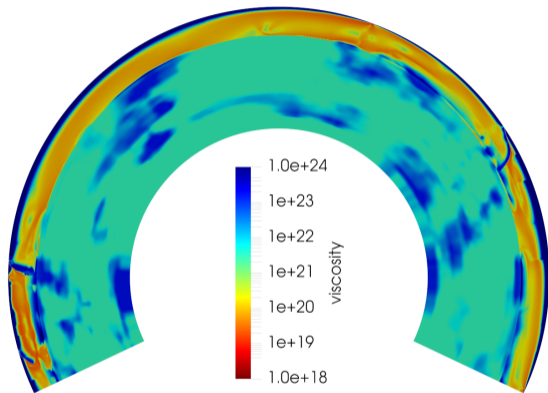
$$\arg \min_m \mathcal{J}(m, u(m)) := \frac{1}{2} \|d - \mathcal{F}(u(m))\|_{\mathcal{C}_{\text{noise}}^{-1}}^2 + \frac{1}{2} \|m - m_{\text{pr}}\|_{\mathcal{C}_{\text{pr}}^{-1}}^2 \quad \text{subject to} \quad \mathcal{A}(m, u(m)) = f$$

- ▶ Construct a Gaussian approximation of $\pi_{\text{post}}(m)$ around this maximum by approximating the Hessian of the optimization problem

Computational results: Inverse problem for a cross sectional model



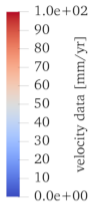
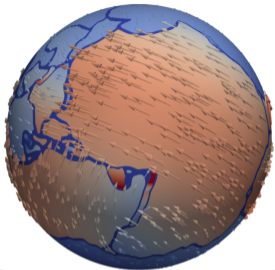
Effective viscosity after inference



▶ Cross sectional model is not able to adequately capture observed physics, i.e., fast motion of stationary South American plate

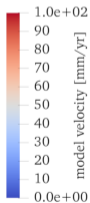
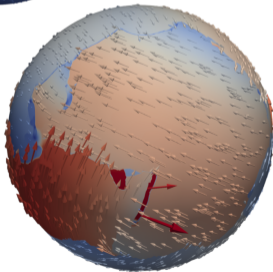
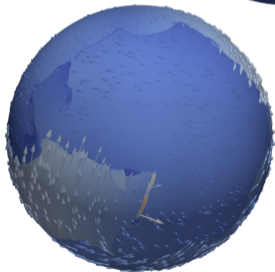
Computational results: Inverse problem for global Earth model

data



parameter inference (at iter. 2)

initial guess



- ▶ Inversion of global scalars (scaling factors, activation energy, stress exponent, yield strength) successfully recovers main trends, i.e., velocities of large plates
- ▶ Local parameters (plate decoupling) remain challenging due to lower sensitivities

Thank you