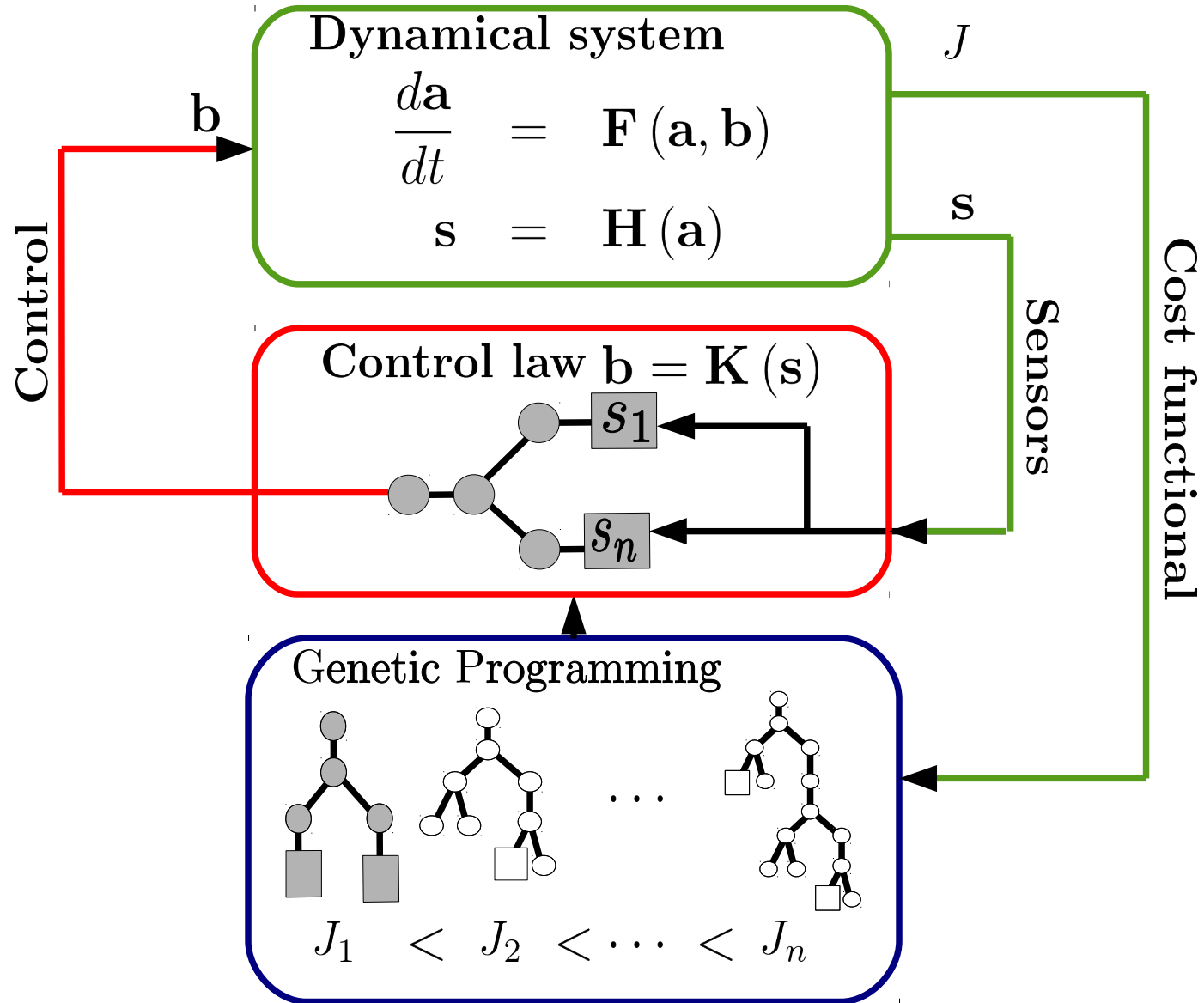


Genetic Programming Control



Genetic programming

- Bio-inspired evolutive algorithm.
- Largely developed by Koza (books, 1994, 1999).
- Regression method which optimizes a function with respect to an objective functional.
- Used in micro-controllers, robotics, programming, weather forecast, fish harvesting, ... --- *almost everywhere except in fluid mechanics.*

Genetic Programming Control 1

MIMO control problem:

$$\frac{d\mathbf{a}}{dt} = \mathbf{F}(\mathbf{a}, \mathbf{b})$$
$$\mathbf{s} = \mathbf{H}(\mathbf{a})$$

Find $b = K(s)$

to minimize $J(\mathbf{a}, \mathbf{b})$

Genetic Programming Control 2

MIMO control problem:

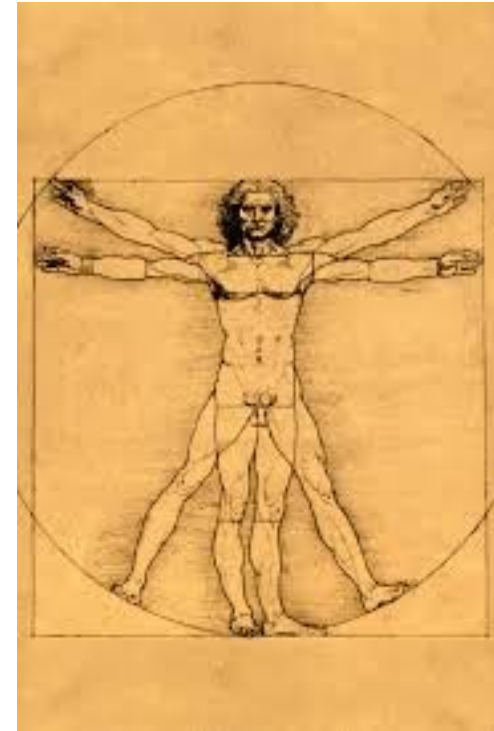
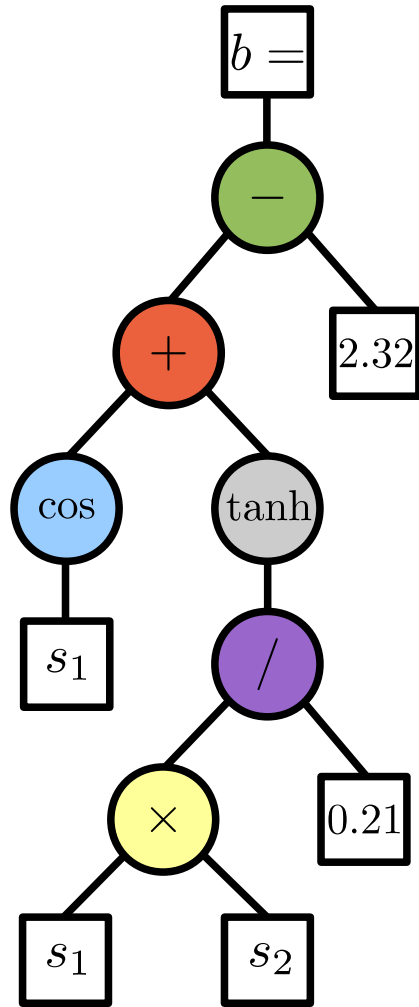
$$\frac{d\mathbf{a}}{dt} = \mathbf{F}(\mathbf{a}, \mathbf{b})$$
$$\mathbf{s} = \mathbf{H}(\mathbf{a})$$

Find $\mathbf{b} = \mathbf{K}(\mathbf{s})$
to minimize $J(\mathbf{a}, \mathbf{b})$



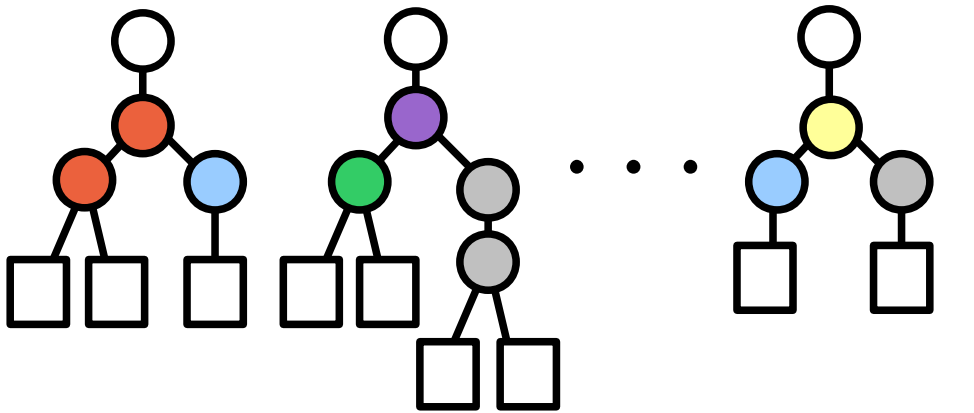
Genetic Programming Control 3

Individual:



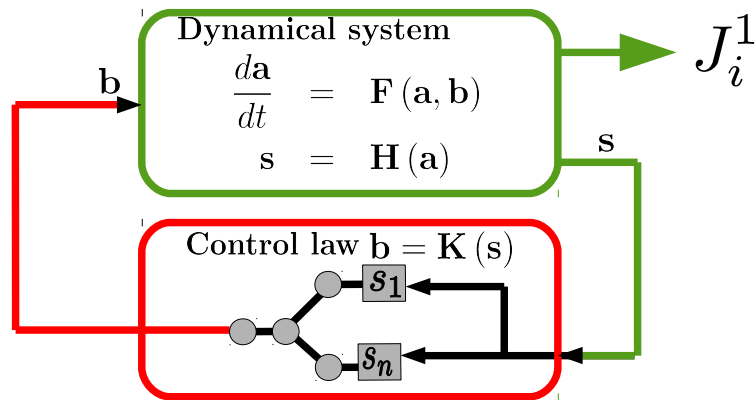
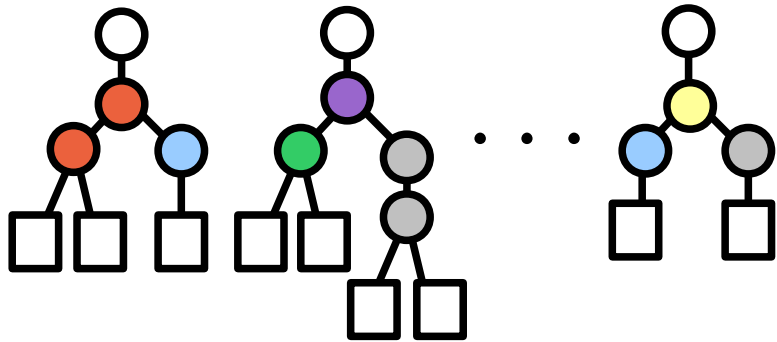
Genetic Programming Control 4

We start with an initial random population:



Genetic Programming Control 5

And evaluate how they solve the problem:



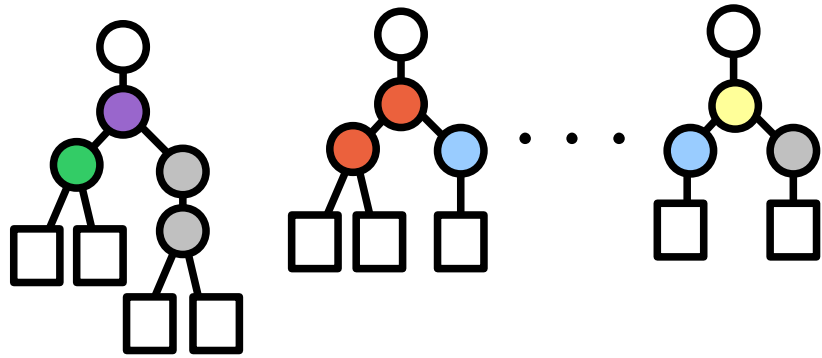
VS



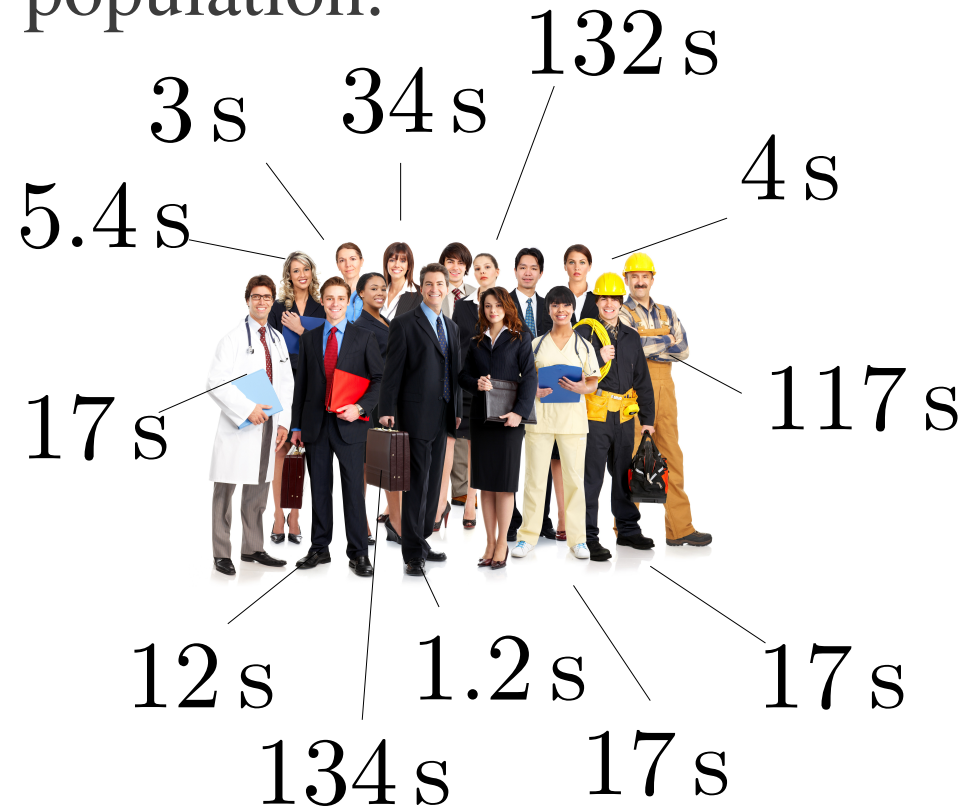
= 17 s

Genetic Programming Control 6

Until we have one evaluated population.



$$J_1^1 < J_2^1 < \dots < J_n^1$$



We need to evolve the population.

Genetic Programming Control 7

We use three genetic operations:

- Replication: copy one individual in the next generation (memory).
- Crossover: change a pair of individuals (exploitation).
- Mutation: change a single individual (exploration).

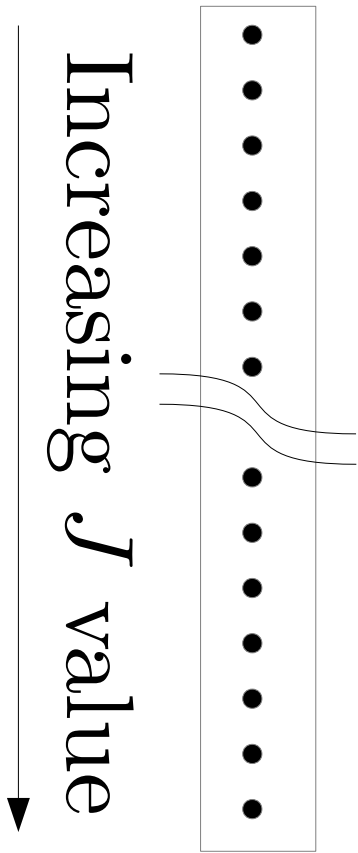
Genetic Programming Control 8

Which individuals get replicated, mutated, crossed?

- The operation gets decided probabilistically.
- The concerned individuals are decided through a random access tournament procedure.
- p individuals are randomly chosen, the best individuals among those are chosen.

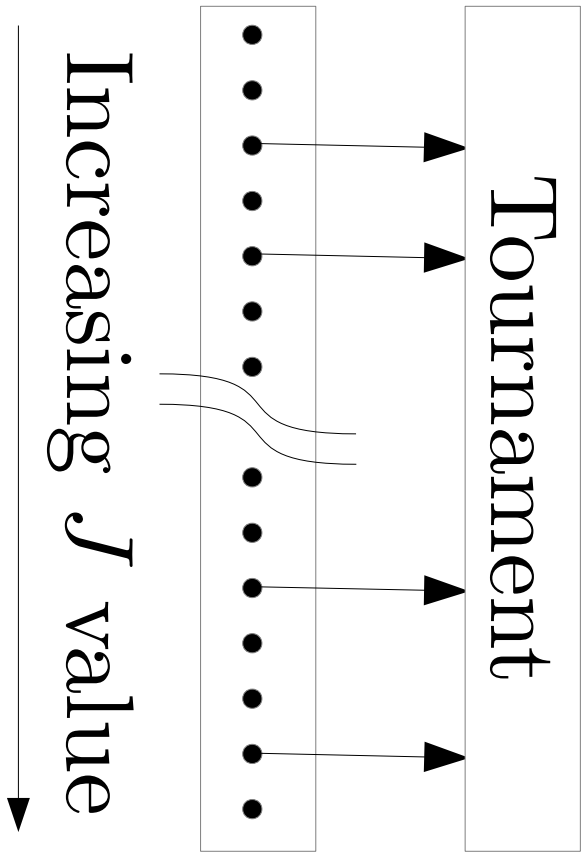
Genetic Programming Control 9

Selection:



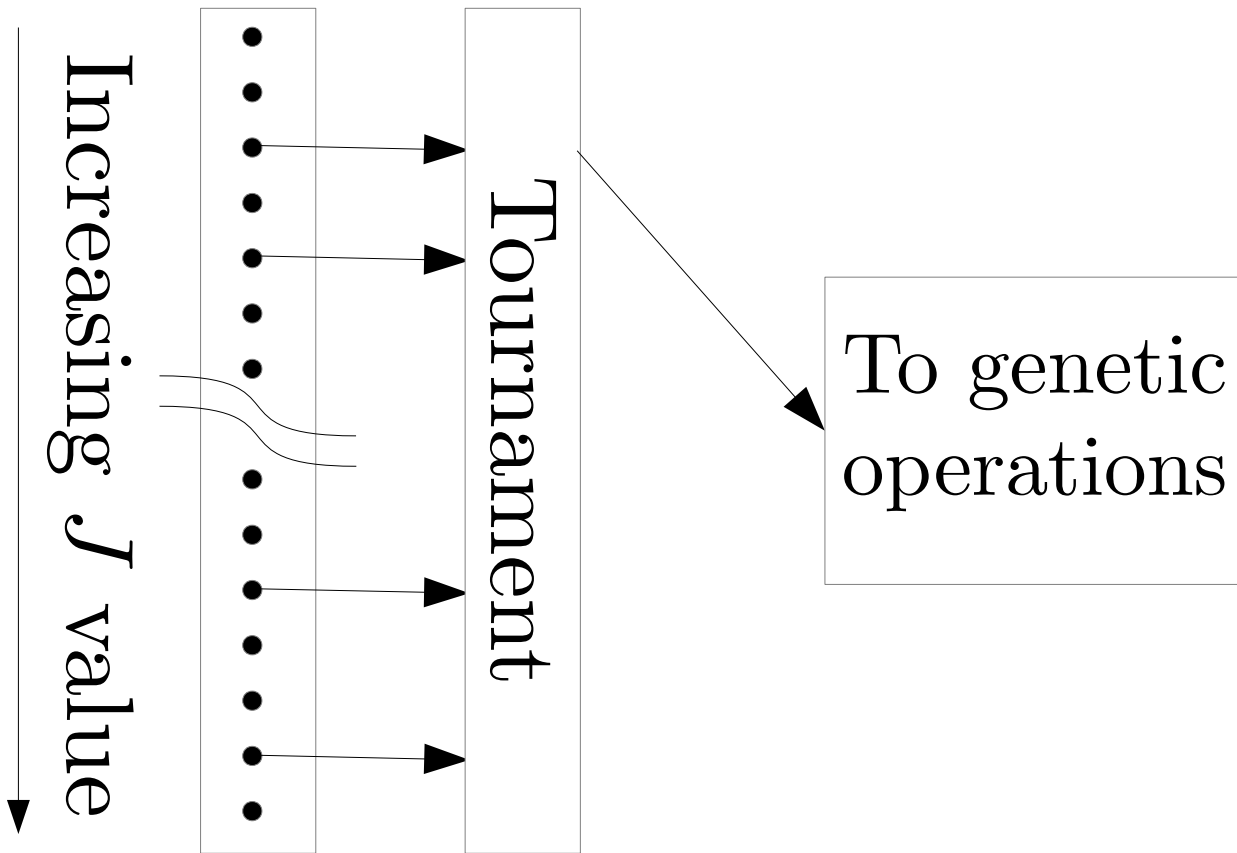
Genetic Programming Control 10

Selection:



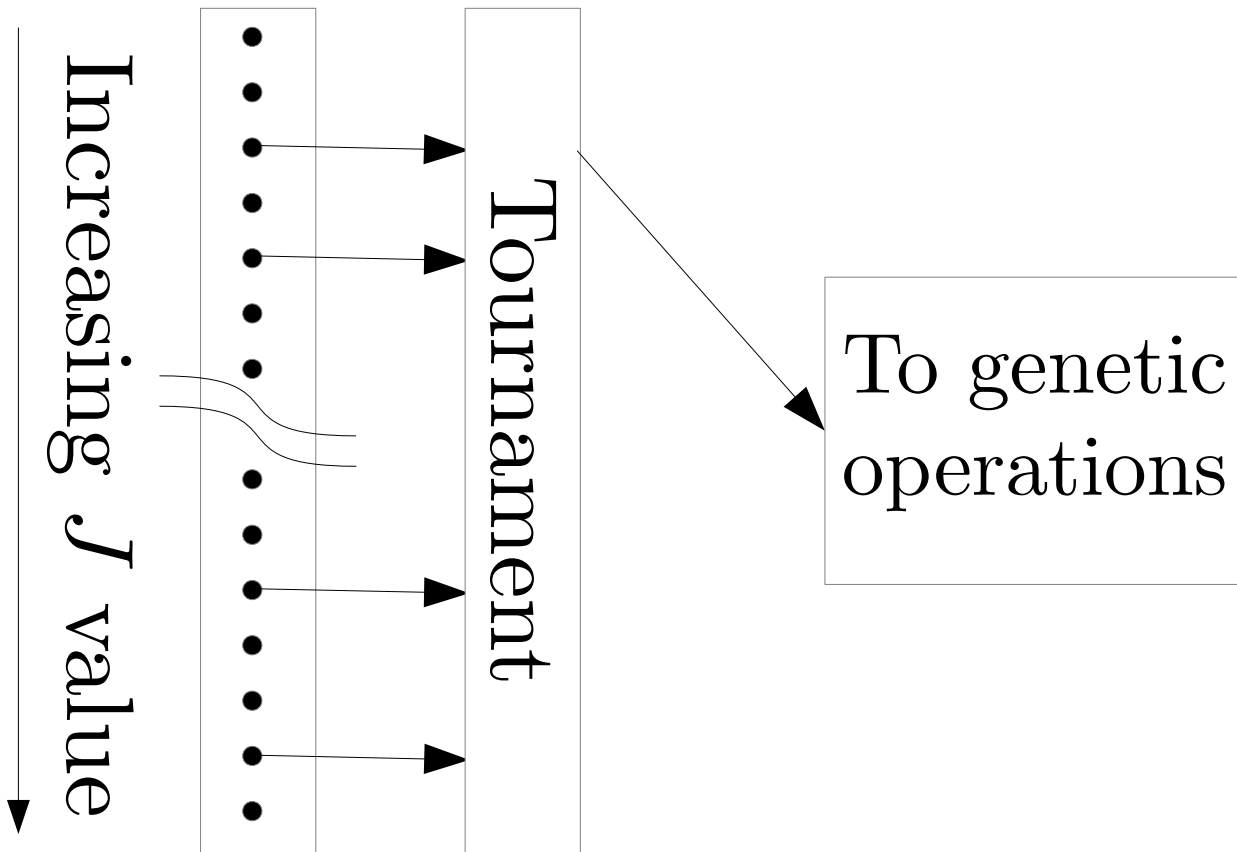
Genetic Programming Control 11

Selection:



Genetic Programming Control 12

Sélection:

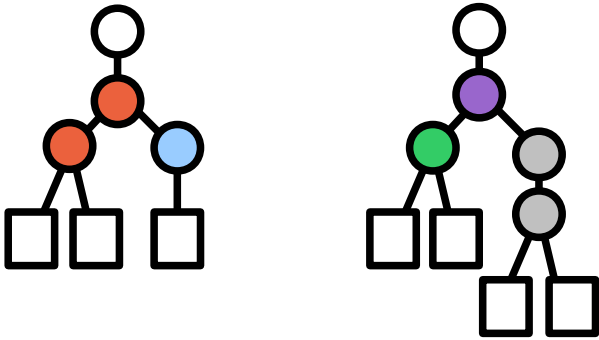


- n individuals
- p individuals in the tournament
- probability for individual i to be selected:

$$P_s(i) = \left(\frac{n - i}{n - 1} \right)^{p-1}$$

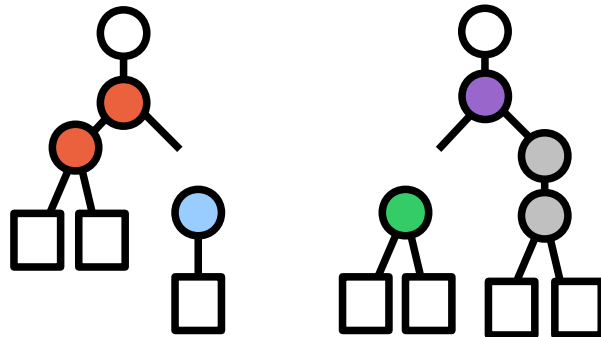
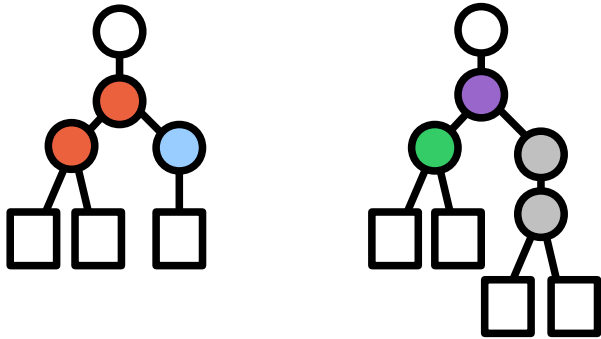
Genetic Programming Control 13

Crossover:



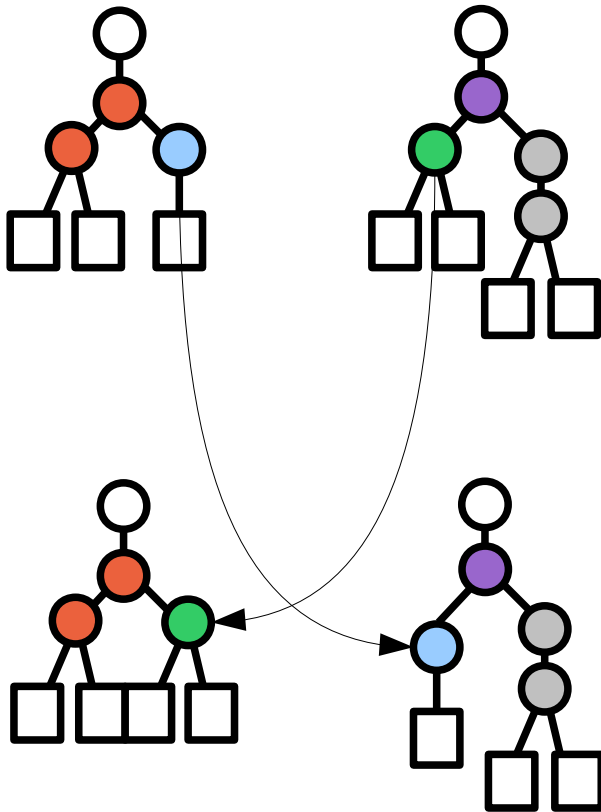
Genetic Programming Control 14

Crossover:



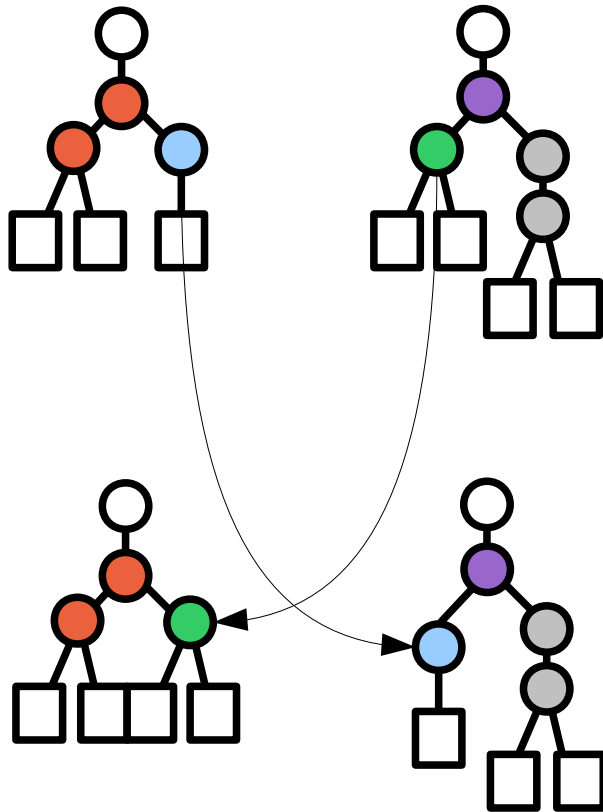
Genetic Programming Control 15

Crossover:



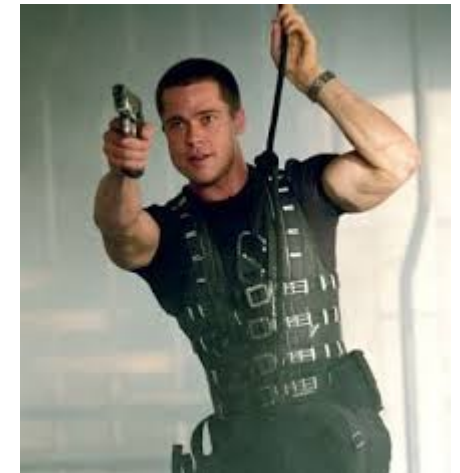
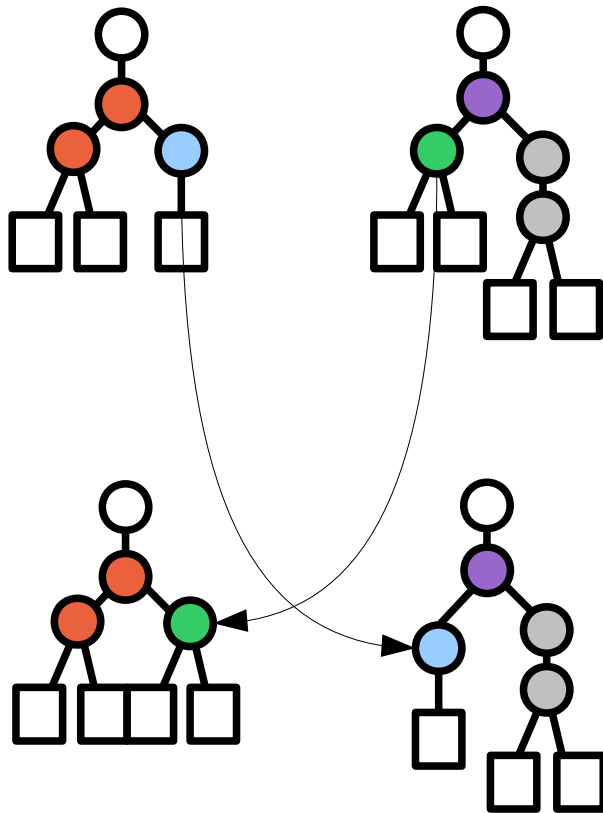
Genetic Programming Control 16

Crossover:



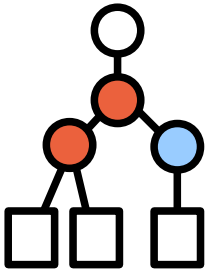
Genetic Programming Control 17

Crossover:



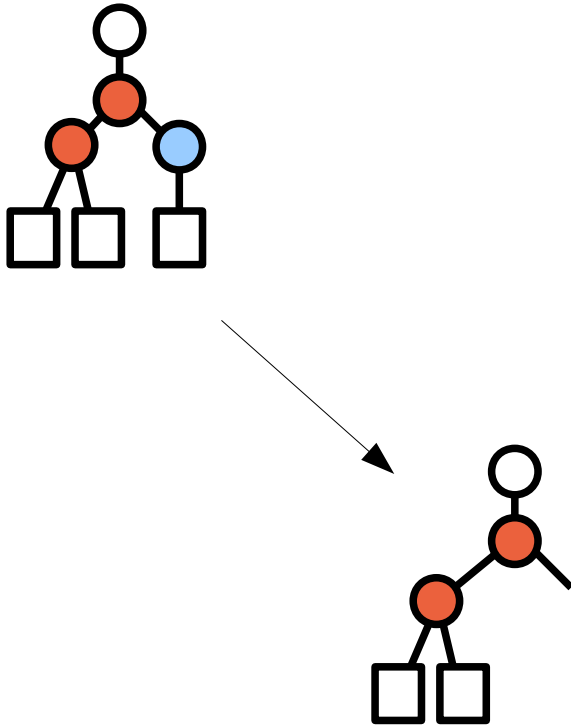
Genetic Programming Control 18

Mutation:



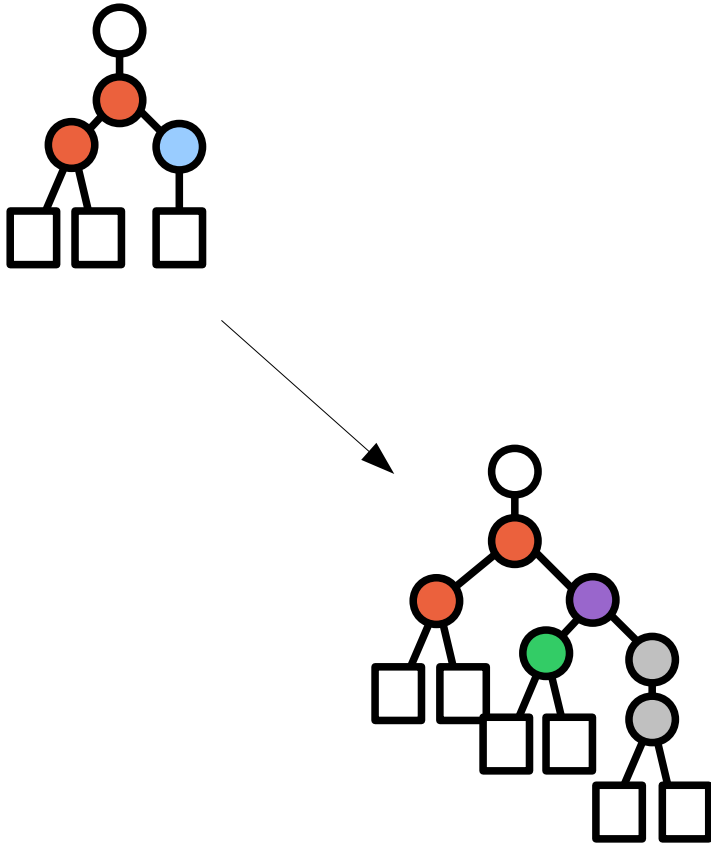
Genetic Programming Control 19

Mutation:



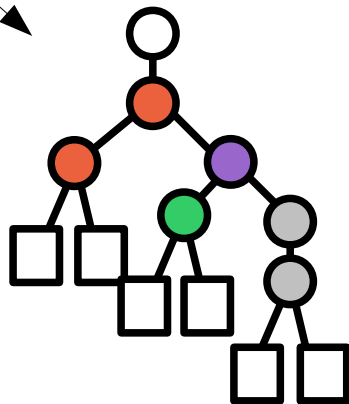
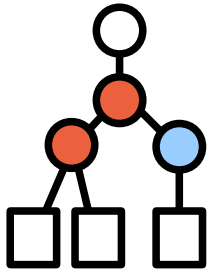
Genetic Programming Control 20

Mutation:



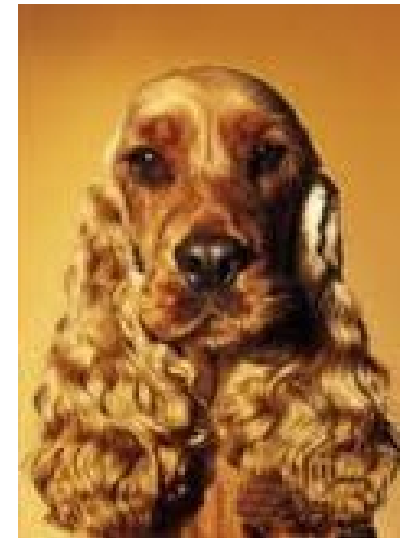
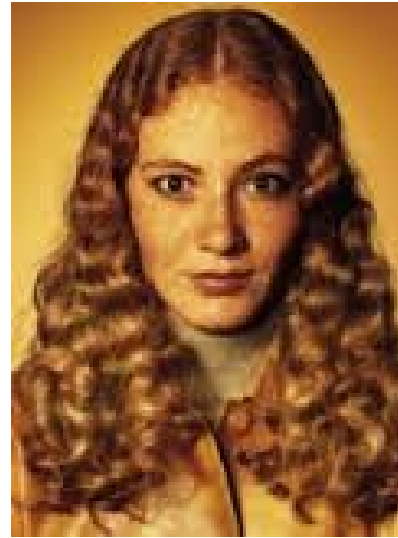
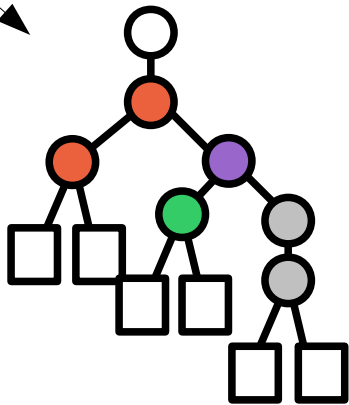
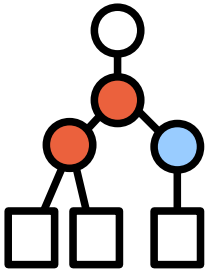
Genetic Programming Control 21

Mutation:

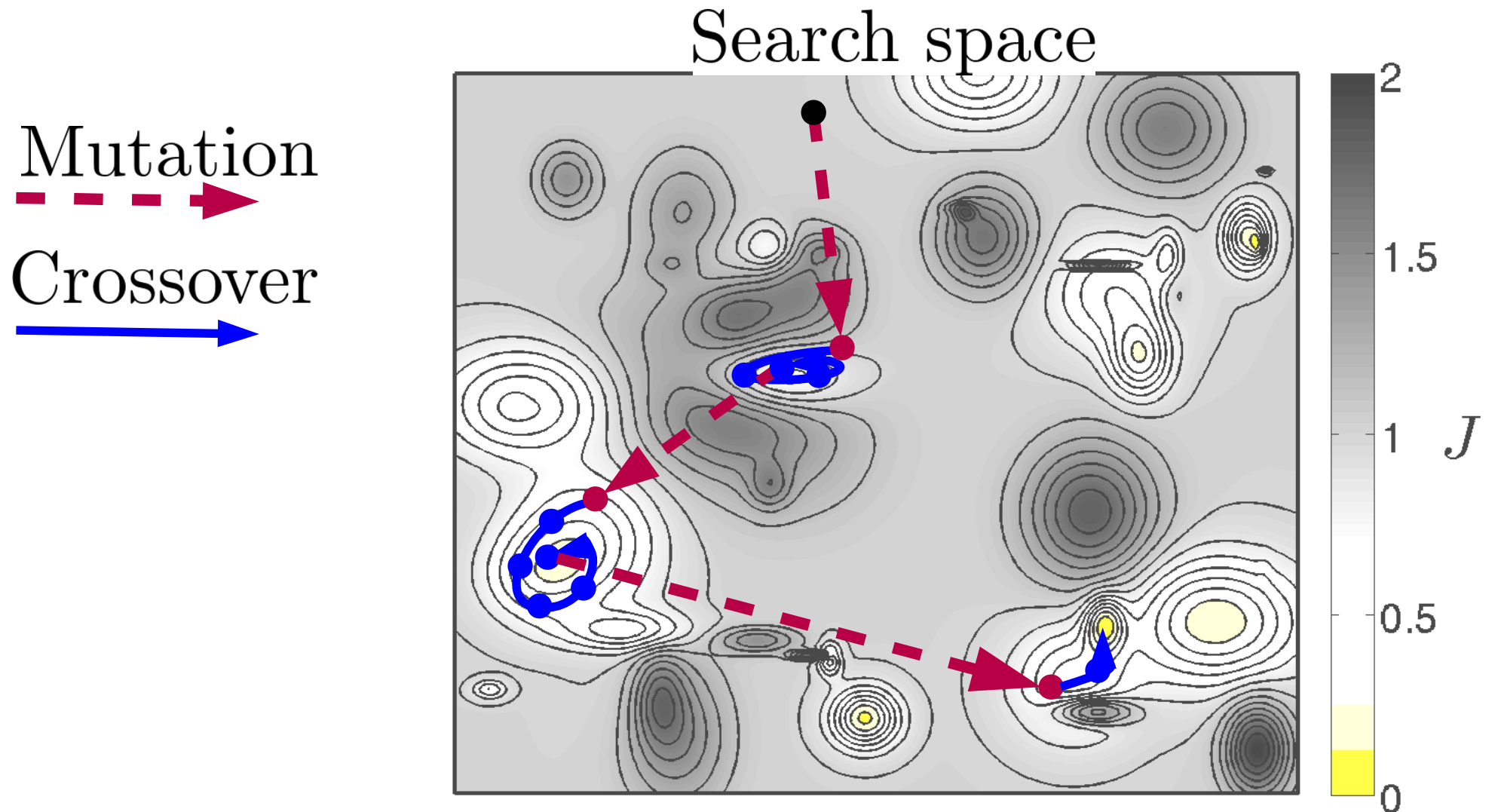


Genetic Programming Control 22

Mutation:

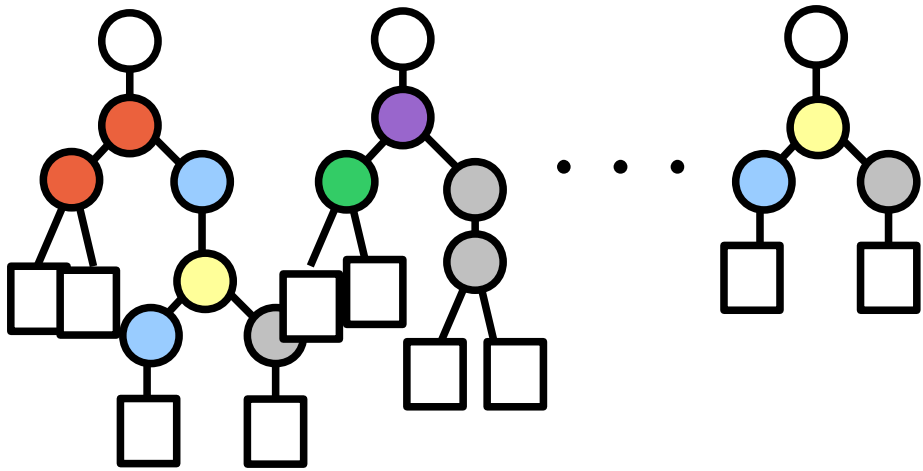


Genetic Programming Control 23



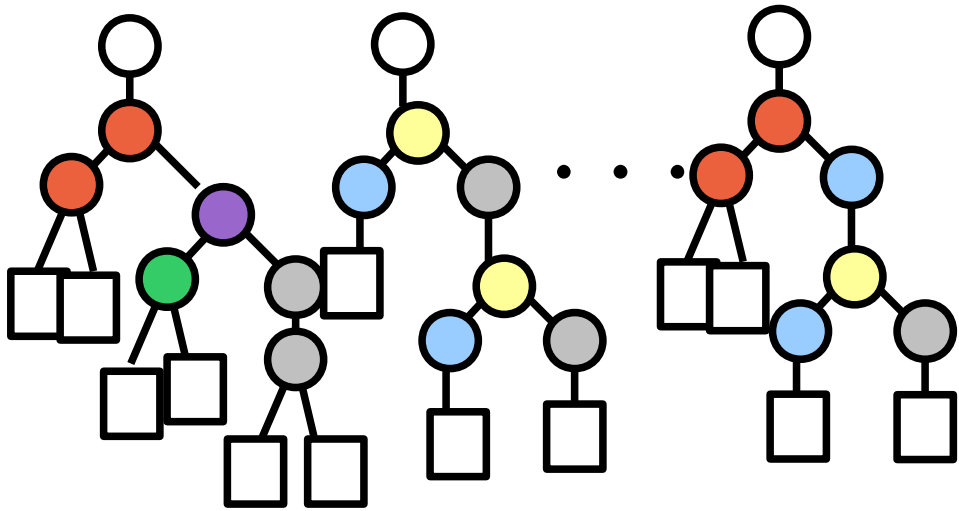
Genetic Programming Control 23

We have a new generation:



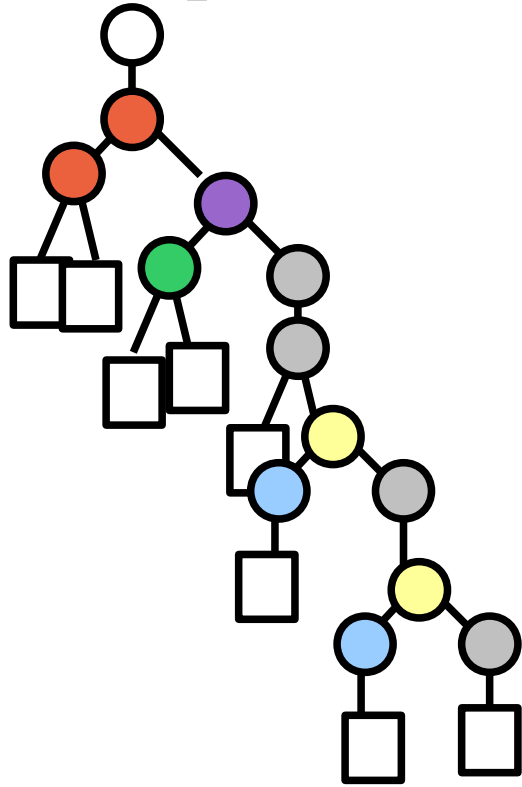
Genetic Programming Control 24

We get increasingly better generations:



Genetic Programming Control 25

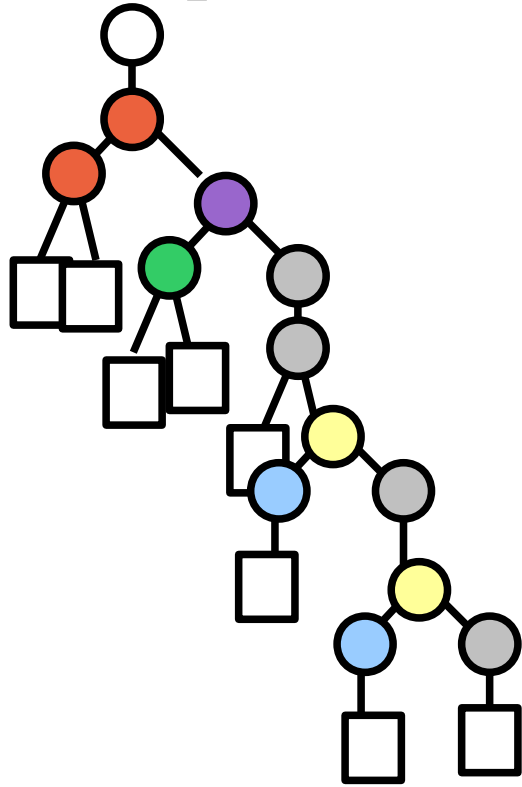
Until the problem is solved



Low enough J value

Genetic Programming Control 26

Until the problem is solved



Low enough J value



Genetic Programming Control 27

