

Iterative Methods for Linear Systems

Comparisons of methods for model problems

GMRES - Computational Cost

GMRES: $\mathbf{A}\mathbf{x} = \mathbf{b}$

choose \mathbf{x}_0 (e.g. $\mathbf{x}_0 = 0$) and tol

$\mathbf{r}_0 = \mathbf{b} - \mathbf{A}\mathbf{x}_0$; $k = 0$; $\mathbf{v}_1 = \mathbf{r}_0 / \|\mathbf{r}_0\|_2$;

while $\|\mathbf{r}_k\|_2 > tol$

$k = k + 1$;

$\mathbf{w} = \mathbf{A}\mathbf{v}_k$;

 Solve $\mathbf{P}\tilde{\mathbf{v}}_{k+1} = \mathbf{w}$;

 for $j = 1 : k$,

$h_{j,k} = \mathbf{v}_j^H \tilde{\mathbf{v}}_{k+1}$;

$\tilde{\mathbf{v}}_{k+1} = \tilde{\mathbf{v}}_{k+1} - h_{j,k} \mathbf{v}_k$;

 end

$h_{k+1,k} = \|\tilde{\mathbf{v}}_{k+1}\|_2$; $\mathbf{v}_{k+1} = \tilde{\mathbf{v}}_{k+1} / h_{k+1,k}$;

4 kernels:

matrix-vector product
preconditioner

inner product

vector update

(norm & vector scaling)

 update QR-dec: $\underline{\mathbf{H}}_k = \underline{\mathbf{Q}}_{k+1} \underline{\mathbf{R}}_k$

$\|\mathbf{r}_k\|_2 = |\tilde{q}_{k+1}^H e_1| \|\mathbf{r}_0\|_2$

end

$\mathbf{y}_k = \underline{\mathbf{R}}_k^{-1} \underline{\mathbf{Q}}_k^H e_1 \|\mathbf{r}_0\|_2$; $\mathbf{x}_k = \mathbf{x}_0 + V_k \mathbf{y}_k$;

$\mathbf{r}_k = \mathbf{r}_0 - V_{k+1} \underline{\mathbf{H}}_k \mathbf{y}_k = V_{k+1} \left(\mathbf{I} - \underline{\mathbf{Q}}_k \underline{\mathbf{Q}}_k^H \right) e_1 \|\mathbf{r}_0\|_2$; (or simply $\mathbf{r}_k = \mathbf{b} - \mathbf{A}\mathbf{x}_k$)

Computational Cost

Many cheap iterations vs minimum number of expensive iterations

Four main kernels

- | | | |
|-------------------------|---------------|---------------------------|
| • matrix-vector product | comp: $2Nk_1$ | comm: neighbor |
| • preconditioner | comp: $2Nk_2$ | comm: neighbor (& global) |
| • vector update | comp: $2N$ | comm: none |
| • inner product | comp: $2N$ | comm: global (reduction) |

Methods for non-Hermitian (nonsymmetric) problems:

- GMRES, GCR, FOM, BiCG, QMR, CGS, BiCGSTAB, TFQMR
- Short recurrence: cheap iteration / many iterations
- Full Orthogonalization: expensive iteration / minimum number

Matrix-vector product often linked to grid / domain partitioning

Partition scheme to minimize comm. volume / nr. of messages

Separate local/nonlocal references and overlap comm. with comp.

MINRES

MINRES: $Ax = b$

choose $x_0 \rightarrow r_0 = b - Ax_0$ and tol , set $k = 0$;

while $\|r_k\| > tol$ do

$k = k + 1$;

$\tilde{v}_{k+1} = Av_k - t_{k,k}v_k - t_{k-1,k}v_{k-1}$;

$t_{k+1,k} = \|\tilde{v}_{k+1}\|_2$; $v_{k+1} = \tilde{v}_{k+1}/t_{k+1,k}$;

Update QR: $Q_{k+1} = Q_k G_k$; $R_k = G_k^H (Q_k^H T_k)$; $\hat{y}_{k,k} = q_k^H \ell_1 \|r_0\|_2$

$\rightarrow Q_k, R_k, \hat{y}_k \equiv Q_k^H \ell_1 \|r_0\|_2$;

$w_k = r_{k,k}^{-1} (v_k - w_{k-1} r_{k-1,k} - w_{k-2} r_{k-2,k})$;

$x_k = x_{k-1} + w_k \hat{y}_{k,k}$

end

Conjugate Gradients

(Easier form of) CG algorithm: $\mathbf{Ax} = \mathbf{b}$

Choose $\mathbf{x}_0 \rightarrow \mathbf{r}_0 = \mathbf{b} - \mathbf{Ax}_0$;

$\mathbf{p}_1 = \mathbf{r}_0; i = 0$

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while || $r_i$ ||2 > tol do
     $i = i + 1$ ;
     $a_i = \frac{\langle r_{i-1}, r_{i-1} \rangle}{\langle p_{i-1}, A p_{i-1} \rangle}$ ;
     $x_i = x_i + a_i p_i$ ;
     $r_i = r_{i-1} - a_i A p_i$ ;
     $\beta_i = \frac{\langle r_i, r_i \rangle}{\langle r_{i-1}, r_{i-1} \rangle}$ ;
     $p_i = r_i - \beta_i p_{i-1}$ ;
end
```

A Model Problem

Convection-Diffusion(-Reaction) Equation

Dirichlet boundary conditions

$$Lu = -(pu_x)_x - (qu_y)_y + ru_x + su_y + tu = f$$

$$\mathbf{u} = \mathbf{u}_n$$

$$\mathbf{u} = \mathbf{u}_w$$

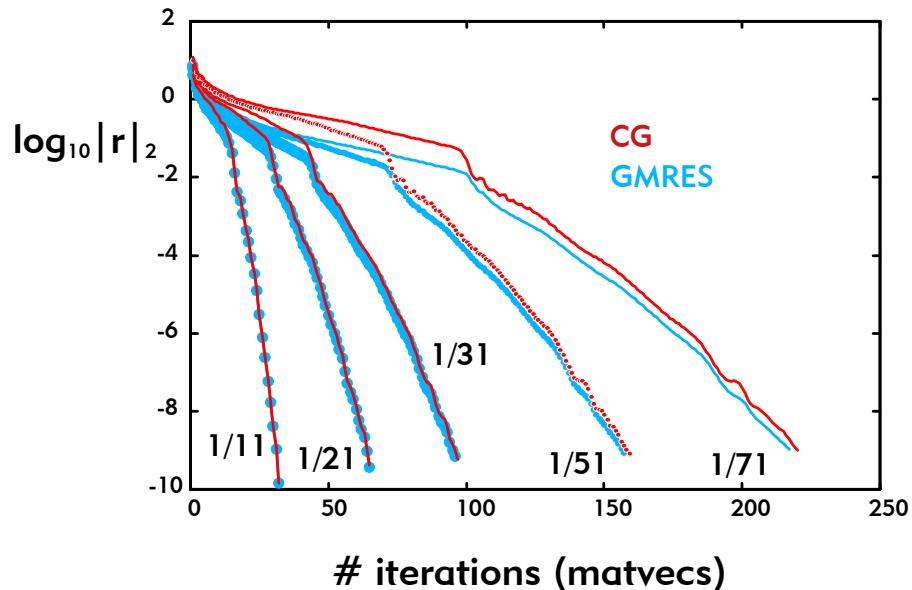
$$Lu = f$$

$$\mathbf{u} = \mathbf{u}_e$$

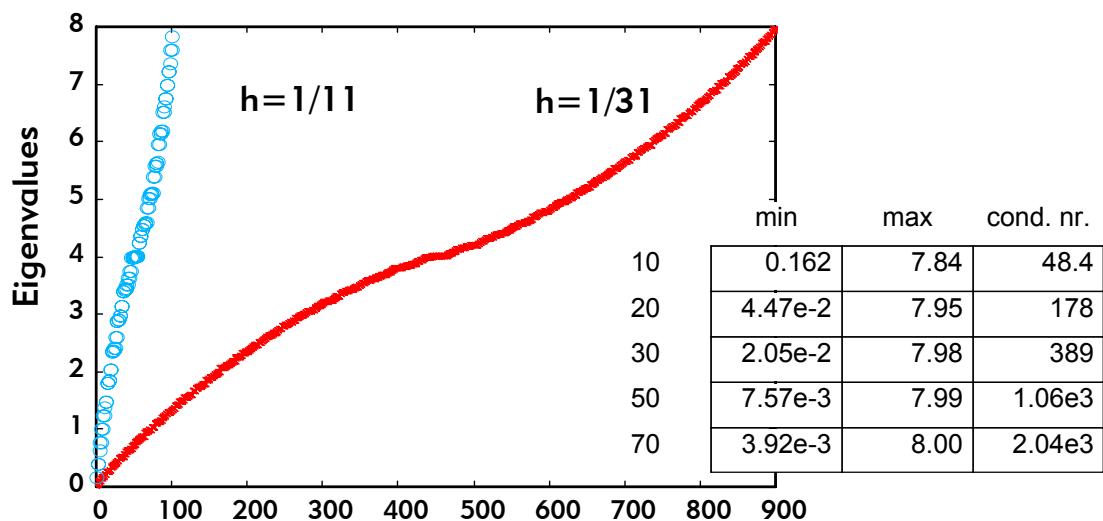
$$\mathbf{u} = \mathbf{u}_s$$

CG vs GMRES for various h

$p=q=1; t = 0; f = 0;$
 $u_s = 0; u_w = 1; u_n = 1; u_e = 0;$



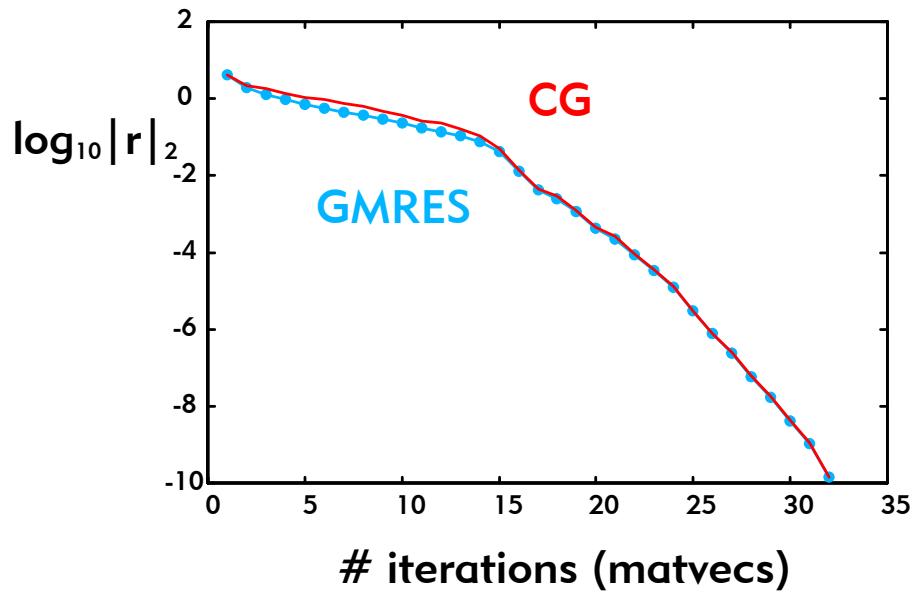
Eigenvalues for various h



CG vs GMRES

$p=q=1; t = 0; f = 0; h=1/11;$

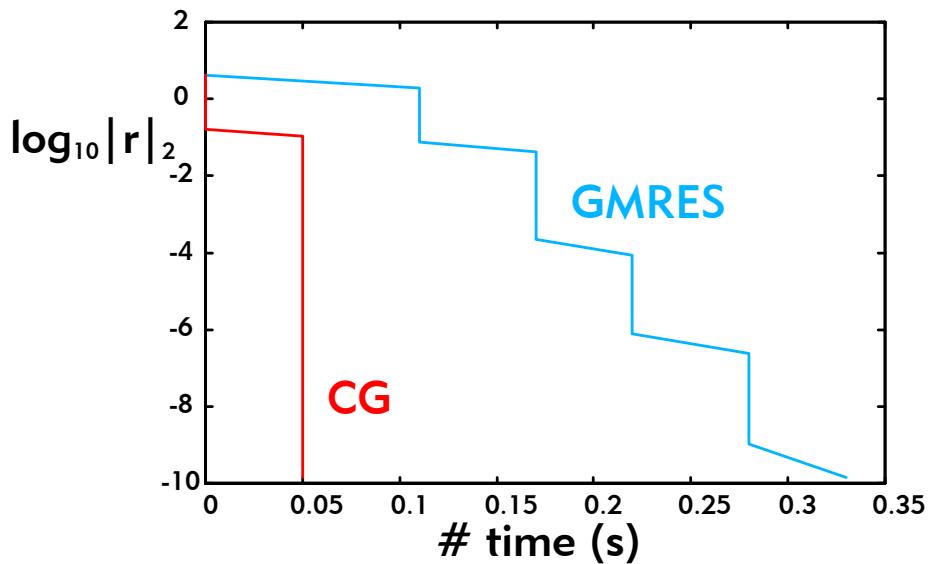
$u_s = 0; u_w = 1; u_n = 1; u_e = 0;$



CG vs GMRES

$p=q=1; t = 0; f = 0; h=1/11;$

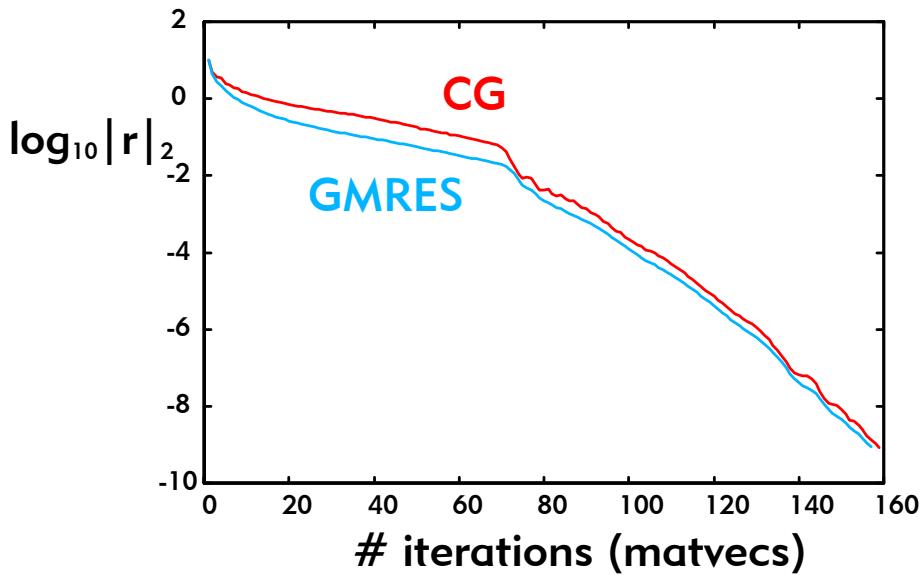
$u_s = 0; u_w = 1; u_n = 1; u_e = 0;$



CG vs GMRES

$p=q=1; t = 0; f = 0; h=1/51;$

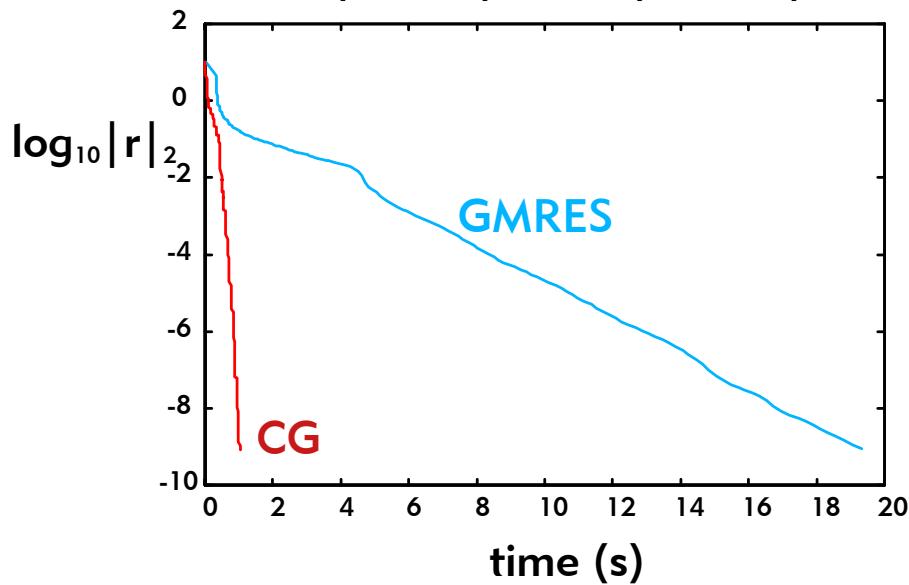
$u_s = 0; u_w = 1; u_n = 1; u_e = 0;$



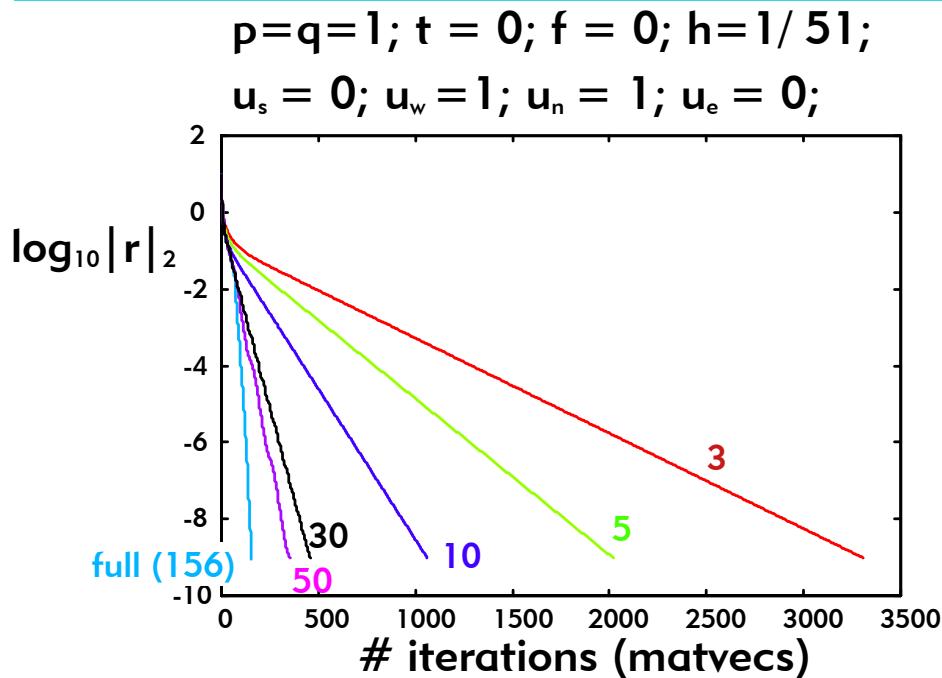
CG vs GMRES (time)

$p=q=1; t = 0; f = 0; h=1/51;$

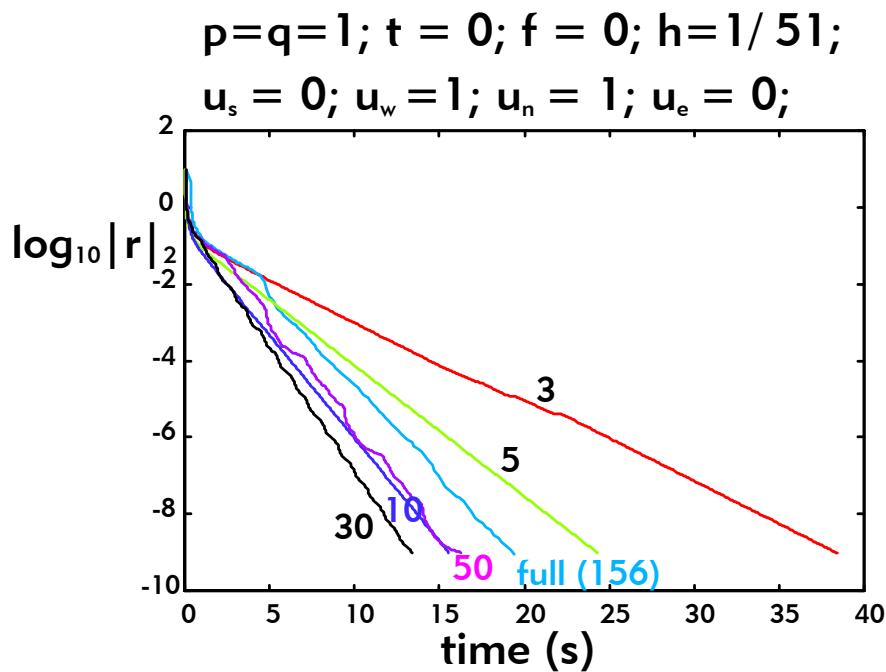
$u_s = 0; u_w = 1; u_n = 1; u_e = 0;$



Iterations for GMRES(m)



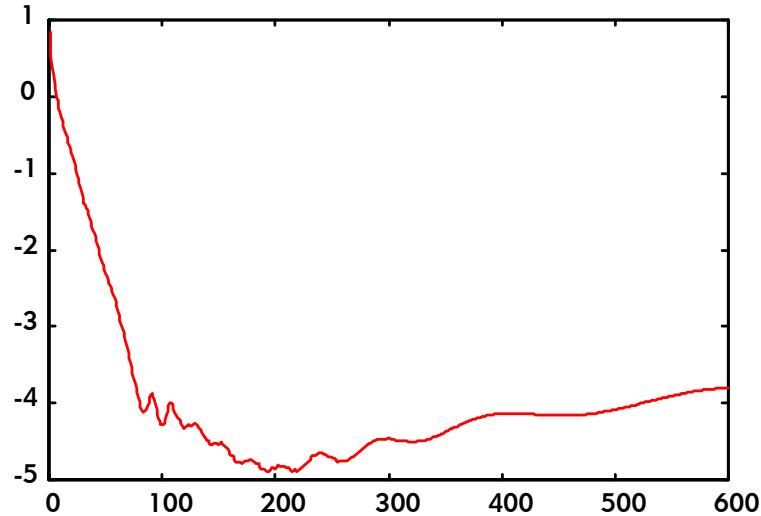
Time for GMRES(m)



CG for non-Hermitian Problem

$p=q=1; r=s=5; h=1/31;$

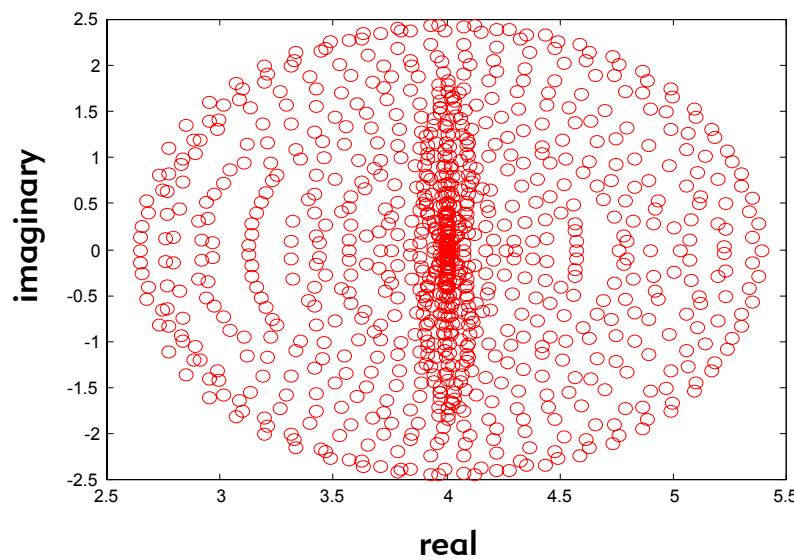
$u_s=0; u_w=0; u_n=1; u_e=1;$



Eigenvalues

$p=q=1; r=s=70; h=1/31;$

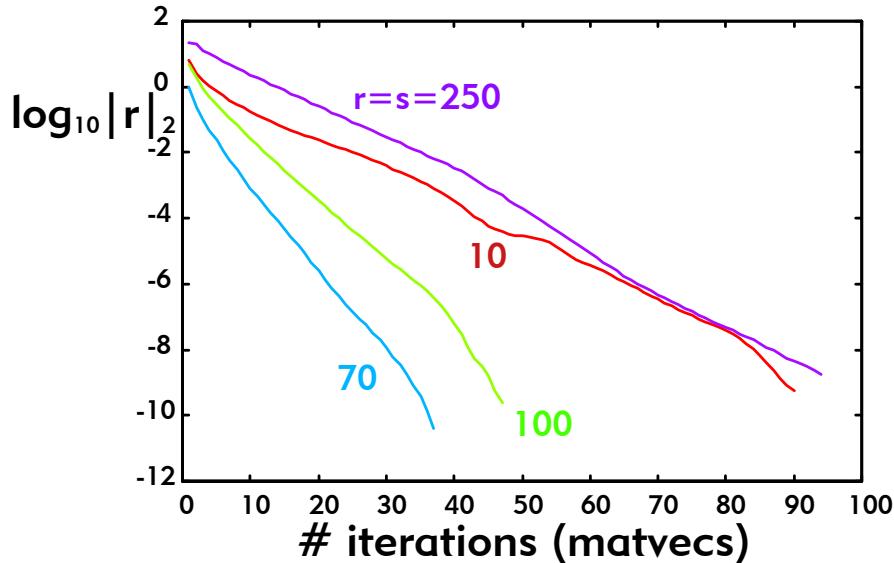
$u_s=0; u_w=0; u_n=1; u_e=1;$



GMRES for varying convection

$p=q=1; r=s:$ given; $h=1/31;$

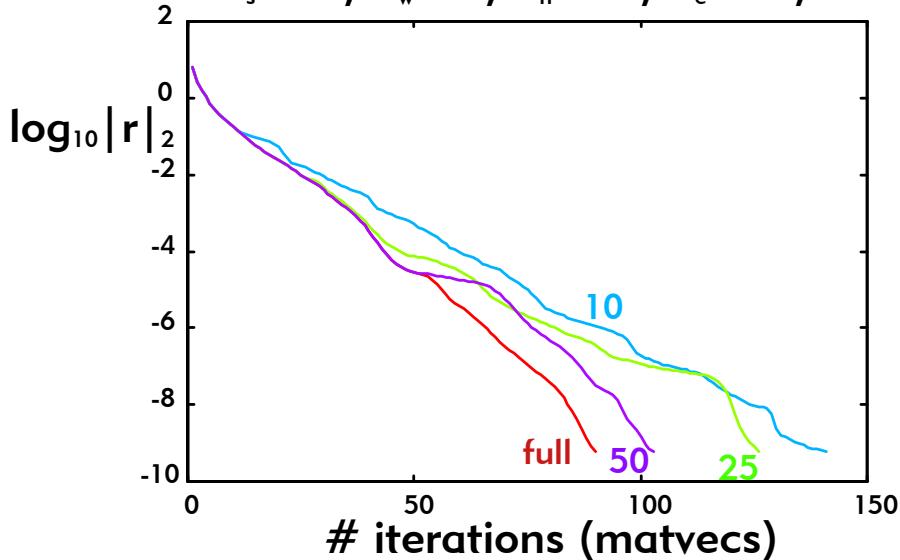
$u_s = 0; u_w = 0; u_n = 1; u_e = 1;$



GMRES(m) with $r=s=10$

$p=q=1; r=s=10; h=1/31;$

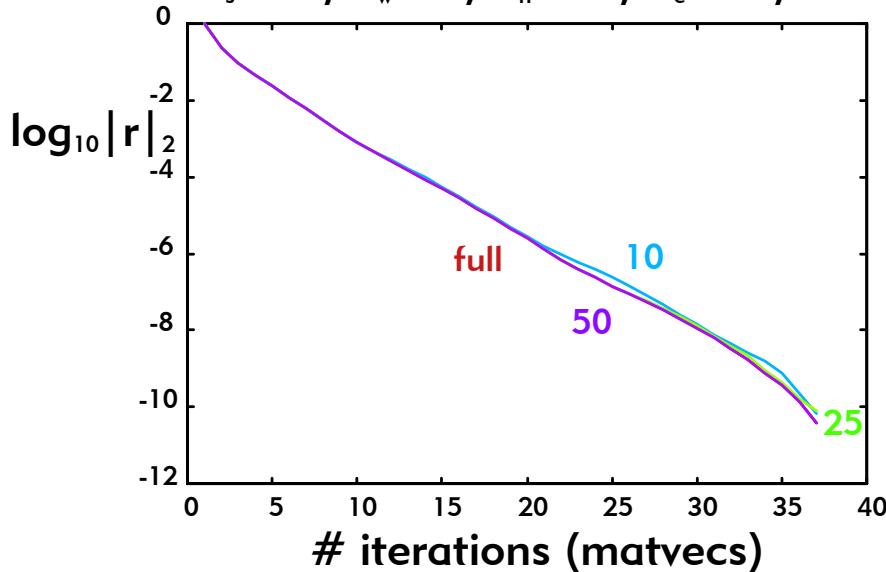
$u_s = 0; u_w = 0; u_n = 1; u_e = 1;$



GMRES(m) with $r=s=70$

$p=q=1; r=s=70; h=1/31;$

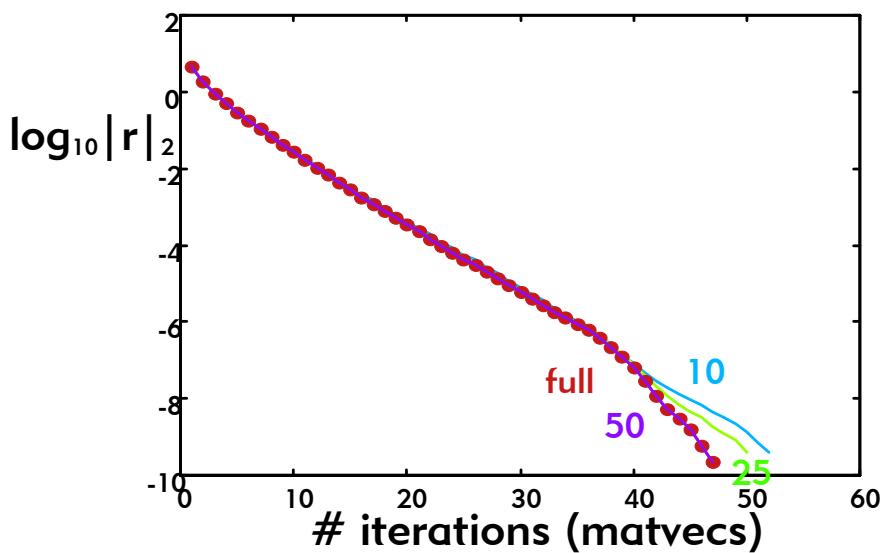
$u_s = 0; u_w = 0; u_n = 1; u_e = 1;$



GMRES(m) with $r=s=100$

$p=q=1; r=s=100; h=1/31;$

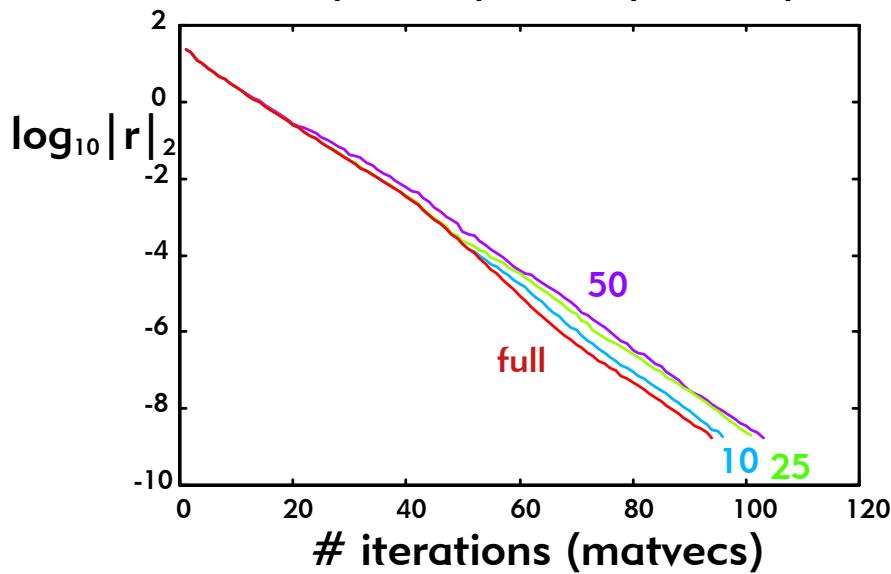
$u_s = 0; u_w = 0; u_n = 1; u_e = 1;$



GMRES(m) with r=s=250

p=q=1; r=s=250; h=1/31;

u_s = 0; u_w = 0; u_n = 1; u_e = 1;

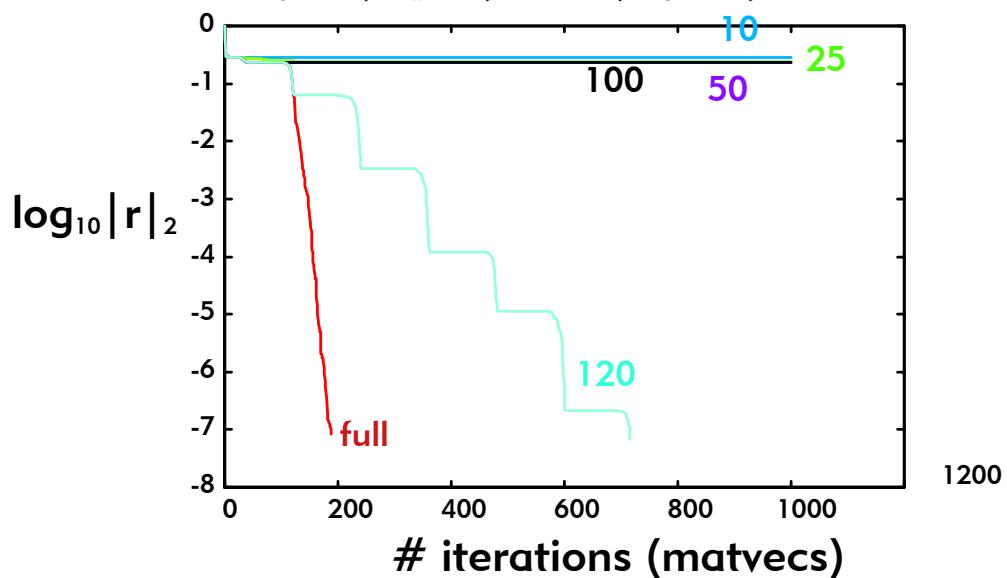


GMRES(m) after shifting spectrum

A=A-3.65*I

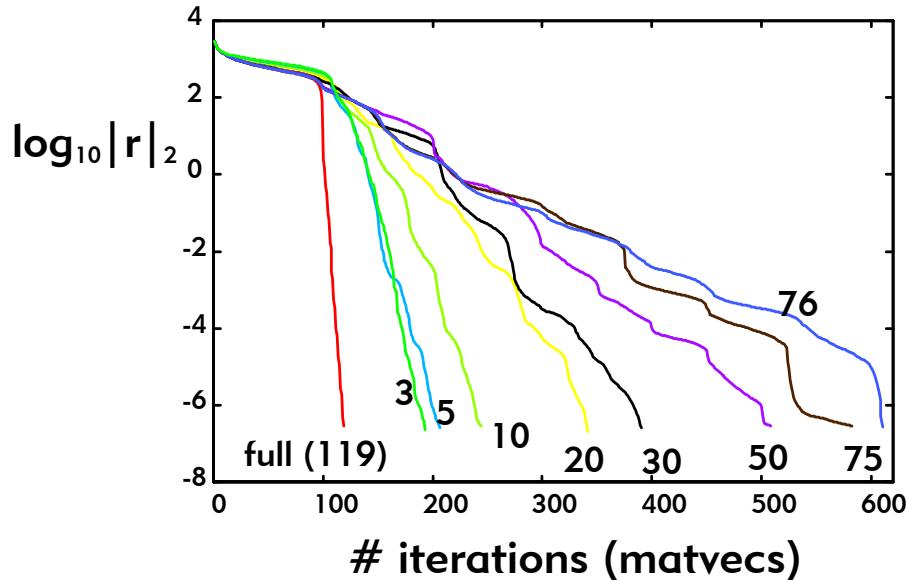
p=q=1; r=s=70; h=1/31;

u_s = 0; u_w = 0; u_n = 1; u_e = 1;



Surprising Convergence of GMRES(m)

$p=q=1; r=200; s=-200; t=0; f=0; h=1/51;$
 $u_s = 0; u_w = 100; u_n = 100; u_e = 0;$



Surprising Convergence of GMRES(m)

$p=q=1; r=200; s=-200; t=0; f=0; h=1/51;$
 $u_s = 0; u_w = 100; u_n = 100; u_e = 0;$

